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LISTING OF THE CLAIMS

1. (Currently Amended) A computer implemented method for predicting the structure of a membrane-bound protein having a plurality of α helical regions, the method comprising:

identifying a range ranges of amino acids in an amino acid sequence of the membranebound protein as transmembrane regions of the membrane-bound protein; constructing each of two or more helices in a set of helices for the transmembrane regions:

obtaining an optimized structure for each of the two or more helices: assembling the optimized structures of the two or more helices into a helix bundle: optimizing a helix-bundle configuration for of the set of helices helix bundle using a first molecular dynamics simulation;

after optimizing the helix bundle configuration, constructing one or more inter-helical loops to generate a full-atom model of the membrane-bound protein; and optimizing the full-atom model using a second molecular dynamics simulation, thereby providing to provide a predicted structure for the membrane-bound protein.

2. (Cancelled).

(Currently Amended) The method of claim 1, wherein the eonstructing each of two or 3. more helices in the set of helices for the transmembrane regions includes one or more of: constructing are each of two or more canonical right-handed α -helices-corresponding to the transmembrane regions, calculating a minimum energy configuration for each of the canonical helices, and optimizing each of the canonical helices.

4 - 34. (Cancelled)

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35. (Currently Amended) The method of claim 1, wherein the optimizing a helix bundle configuration of the helix bundle includes one or more of:

assembling a helix bundle including each of the set of helices, and calculating a minimum-energy configuration for the helix bundle in a lipid bilayer.

- 36 (Previously Presented) The method of claim 1, wherein: the membrane-bound protein is a G-protein coupled receptor.
- 37. (Currently Amended) The method of claim 1, wherein: identifying a range ranges of amino acids in the amino acid sequence as transmembrane regions includes aligning the amino acid sequence with an experimental or theoretical helical template.
- 38. (Currently Amended) The method of claim 1, wherein: wherein identifying a range of amino acids in the amino acid sequence as transmembrane regions includes includes: determining the periodicity of hydrophobic residues in the amino acid sequence; and optimizing a helix bundle configuration includes identifying a plurality of lipid-accessible residues based at least in part on the determined periodicity.
- 39. (Currently Amended) The method of claim 1, wherein: constructing obtaining an optimized structure for each of the two or more helices in a set of helices for the transmembrane regions includes optimizing each of the two or more helices in the set of helices using a torsional molecular dynamics method.
- 40. (Previously Presented) The method of claim 39, wherein: the torsional molecular dynamics method uses the Newton-Euler Inverse Mass Operator.
- (Currently Amended) The method of claim 1, wherein: 41.

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constructing each of two or more helices in a set of helices for the transmembrane regions obtaining an optimized structure for each of the two or more helices includes determining 3-D coordinates that define the structure of <u>for</u> each <u>of the two or more</u> helix in the set of helices.

(Currently Amended) The method of claim 1, wherein:
 optimizing assembling the optimized structures of the two or more helices into a helix bundle configuration includes determining a rotation and tilt of each helix in the set of helices.

- 43. (Currently Amended) The method of claim 1, wherein: optimizing assembling the optimized structures of the two or more helices into a helix bundle configuration includes orienting the helix axes of the two or more helices according to the 7.5 Å electron density map for rhodopsin.
- 44. (Currently Amended) The method of claim 38, wherein: optimizing assembling the optimized structures of the two or more helices into a helix bundle configuration includes orienting the identified lipid-accessible residues to face the outside of the helix bundle.
- (Previously Presented) The method of claim 1, wherein:
 the first molecular dynamics simulation is a rigid body molecular dynamics simulation.
- 46. (Currently Amended) The method of claim 1, wherein: optimizing assembling the optimized structures of the two or more helices into a helix bundle configuration for the set of helices includes modeling an effect of an environment of the membrane-bound protein, wherein the effect of the environment is simulated with a continuum description of a water environment and a lipid bilayer.

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simulation.

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47. (Currently Amended) The method of claim 45, wherein:

> the first molecular dynamics simulation uses [[the]] a DREIDING force field, charges derived from charge equilibriation to simulate lipids in the membrane, and charges from CHARMM22 for the membrane-bound protein.

48. (Currently Amended) The method of claim [[1,]] 47, wherein: the second molecular dynamics simulation is a mixed mode molecular dynamics

49. (Currently Amended) The method of claim 48, wherein the mixed mode molecular dynamics includes:

the second molecular dynamics simulation uses a torsional molecular dynamics method to model modeling the helices and inter-helical loops with a torsional molecular dynamics method; and

a rigid body molecular dynamics method to model treating lipids in the [[a]] membrane in which the membrane bound protein is situated as rigid bodies, and counterions Na and Cl as free cartesian atoms;

simulating the outside of the lipids with surface-generalized Born model continuum solvent description;

performing constant temperature dynamics with Hoover algorithm for 50 ps with time steps of 1 and 5 fs; and

using a dielectric constant of 60.0 to simulate the low dielectric region surrounding the membrane.

50. (Currently Amended) The method of claim 1, wherein; wherein the second molecular dynamics simulation includes:

dynamic optimization of the structure using cell multipole methods for calculation of nonbond forces, and [[or]]

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fast torsional dynamic methods <u>selected from Newton-Euler Inverse Mass Operator and</u>
<u>Hierarchical Newton-Euler Inverse Mass Operator</u>.

- (Previously Presented) The method of claim 1, wherein:
 at least the second molecular dynamics simulation includes a solvent approximation.
- (Previously Presented) The method of claim 51, wherein: the solvent approximation is a continuum solvation model.
- (Previously Presented) The method of claim 52, wherein:
 the solvent approximation includes the Surface Generalized Born model or the Poisson-Boltzmann description.
- 54. (Previously Presented) The method of claim 53, wherein: the solvent approximation is an empirical approximation comprising estimating solvation free energy as a function of solvent accessible protein surface area.
- 55. (Previously presented) The method of claim 1, wherein: the second molecular dynamics simulation is performed for a time in the range from about 100 ps to about 1 ns.
- (Previously presented) The method of claim 1, wherein:
 the set of helices includes four or more membrane-spanning α-helices.
- 57. (Previously presented) The method of claim 1, wherein: the set of helices includes seven membrane-spanning α -helices.
- (Cancelled)

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59. (Currently Amended) The method of claim [[50,]] 1, wherein the optimizing the full-atom model further includes:

prior to the second molecular dynamics simulation,
performing a full atom minimization of the full-atom model with a barrel of lipid
surrounding the protein is performed.

- (Previously presented) The method of claim 1, wherein the amino acid sequence of the membrane-bound protein is obtained from GeneBank.
- (Previously presented) The method of claim 1, wherein the predicted structure is output in protein data bank format.
- 62. (Previously presented) A programmable digital computer, configured to perform the method of claim 1.
- 63. (New) A computer program product tangibly embodied in a machine-readable storage device, wherein the computer program includes instructions for executing the method of claim 1 on a programmable processor.
- (New) The method of claim 45, wherein the rigid body dynamics is carried out for 150 ps.